

Introduction to Engineering Optimization (ME6806)



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Methods Requiring Derivatives



- Newton–Raphson Method
- Bisection Method
- Secant Method
- Cubic Search Method

Newton-Raphson Method







Newton-Raphson Method

Consider the problem

Minimize
$$f(x) = 2x^2 + \frac{16}{x}$$

Suppose we use the Newton–Raphson method to determine a stationary point of f(x) starting at the point $x_1 = 1$:

$$f'(x) = 4x - \frac{16}{x^2}$$
 $f''(x) = 4 + \frac{32}{x^3}$

Newton-Raphson Method



Step 1.
$$x_1 = 1$$
 $f'(x_1) = -12$ $f''(x_1) = 36$
 $x_2 = 1 - \frac{-12}{36} = 1.33$
Step 2. $x_2 = 1.33$ $f'(x_2) = -3.73$ $f''(x_2) = 17.6$
 $x_3 = 1.33 - \frac{-3.73}{17.6} = 1.54$

We continue until $|f'(x_k)| < \varepsilon$, where ε is a prespecified tolerance.

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• Bisection Method = a numerical method in Mathematics to find a root of a given *function*

• Root of a function f(x) = a value *a* such that:

f(a) = 0

Function: $f(x) = x^2 - 4$

Roots: x = -2, x = 2

Because:

$$f(-2) = (-2)^2 - 4 = 4 - 4 = 0$$

$$f(2) = (2)^2 - 4 = 4 - 4 = 0$$

• If a function f(x) is continuous on the interval [a..b] and sign of $f(a) \neq \text{sign of } f(b)$, then:

• There is a value $c \in [a..b]$ such that: f(c) = 0 i.e., there is a root c in the interval [a..b]





- The Bisection Method is a *successive* approximation method that narrows down an interval that contains a root of the function f(x).
- The Bisection Method is *given* an initial interval [a..b] that contains a root (We can use the property sign of $f(a) \neq \text{sign of } f(b)$ to find such an initial interval).
- The Bisection Method will *cut the interval* into 2 halves and check which half interval contains a root of the function.
- The Bisection Method will keep *cut the interval* in halves until the resulting interval is extremely small.

The root is then *approximately equal* to *any value* in the final (very small) interval.

2/10/2021

48

Bisection Method - Introduction









Because sign of f(m) ≠ sign of f(a), we proceed with the search in the new interval [a..b]:



We can use this statement to change to the new interval:

- In the this example, we have changed the end point *b* to obtain a smaller interval that still contains a root.
- In other cases, we may need to changed the end point *b* to obtain a smaller interval that still contains a root.





• After cutting the interval in half, the root is contained in the right-half, so we have to change the end point *a*:





Given: interval [a..b] such that: sign of $f(a) \neq sign of f(b)$ (i.e.: replace a with m)

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repeat (until the interval [a..b] is "very small")
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a+b m = -----; // m = midpoint of interval [a..b] 2

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if ( sign of f(m) ≠ sign of f(b) )
{
    use interval [m..b] in the next iteration
```

```
}
else
{
    use interval [a..m] in the next iteration (i.e.:
replace b with m)
}
```

Approximate root = (a+b)/2; (any point between [a..b] will do because the interval [a..b] is very small)

Bisection Method



Determine two points L and R such that f'(L) < 0 and f'(R) > 0. The stationary point is between the points L and R. We determine the derivative of the function at the midpoint,

$$z = \frac{L+R}{2}$$

If f'(z) > 0, then the interval (z, R) can be eliminated from the search. On the other hand, if f'(z) < 0, then the interval (L, z) can be eliminated. We shall now state the formal steps of the algorithm.

Given a bounded interval $a \le x \le b$ and a termination criterion ε :

Step 1. Set R = b, L = a; assume f'(a) < 0 and f'(b) > 0. Step 2. Calculate z = (R + L)/2, and evaluate f'(z). Step 3. If $|f'(z)| \le \varepsilon$, terminate. Otherwise, if f'(z) < 0, set L = z and go to step 2. If f'(z) > 0, set R = z and go to step 2.